

# **COBOT PALLETIZER**



ROBOTICS | MACHINES | SERVICES

MIDDLE EAST AFRICA

### **FEATURES**



The mobile collaborative palletizer combines a palletizing cell with a collaborative robot making the cell safe for humans to work around without safety cages or safety scanners. This is an economical approach to palletizing needs in manufacturing.





#### **SAFETY**

Collaborative robots are safe to work with due to sensitive contact detection

#### **MOBILITY**

This cobot can move between lines and be positionedwithin minutes

#### **CONTINUOUS PRODUCTION**

With two pallet building locations, this keeps the palletizer continuously working

#### **OPTIONS & ACCESSORIES**

- Slip Sheet standard option
- Multiple tooling options
- Case Infeed Conveyor



6-axis-robot for dynamic palletizing / depalletizing on up to 2 pallets

### **TECHNICAL SPECIFICATIONS**

Products Cardboxes, trays and other fixed packages,

which can begripped with a vaccum suction device;

For products such as paper stacks, magazines or trays other gripping devices are needed.

System 6-axis-robot suitable for human-robot collaboration

without fixed installed safely fence; provides highest

security by power and moment monitoring via

absolute precise pulse codes in all joints

Product width 100 - 300 mm (optionally also larger)

Product length 100 - 600 mm Stack height 50 - 600 mm

Stack weight max. 9kg (depending on gripping device)

Pallet format 800 x 1200 mm (pallets must be in good shape)

Palletizing height max. 1800 mm incl. pallet

Empty pallet height 130 mm (min.) - 150 mm (max.)

Speed max. 6 products (batches)/min. in cobot-mode

(without safely equipment)

max. 11 batches (batches)/min. in robot-mode

(with safely equipment)

Carriage capacity max. 20 kg
Repetion accuracy max. +/- 0.10 mm
Operating distance max. 1200 mm

Drive 6 controlled Servo axes

Voltage 1,2 kVA at 380-440 V / NPE, 50Hz / 60Hz.

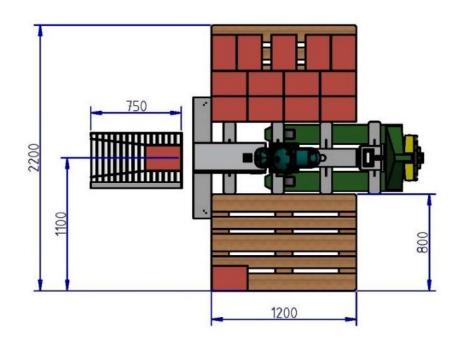
Security 3 x 16 A, slow blow fuse

Air pressure min. 6 bar

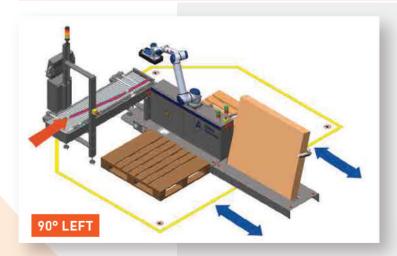
Air consumption depending on gripping device

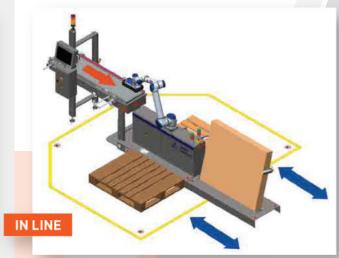
## **CELL LAYOUT**

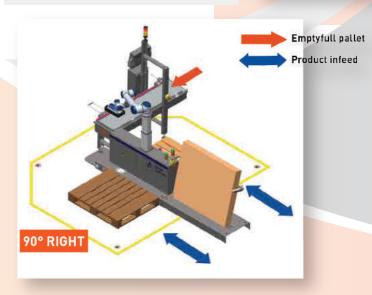




## **MULTI-CONFIGURATION CELL LAYOUT**









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